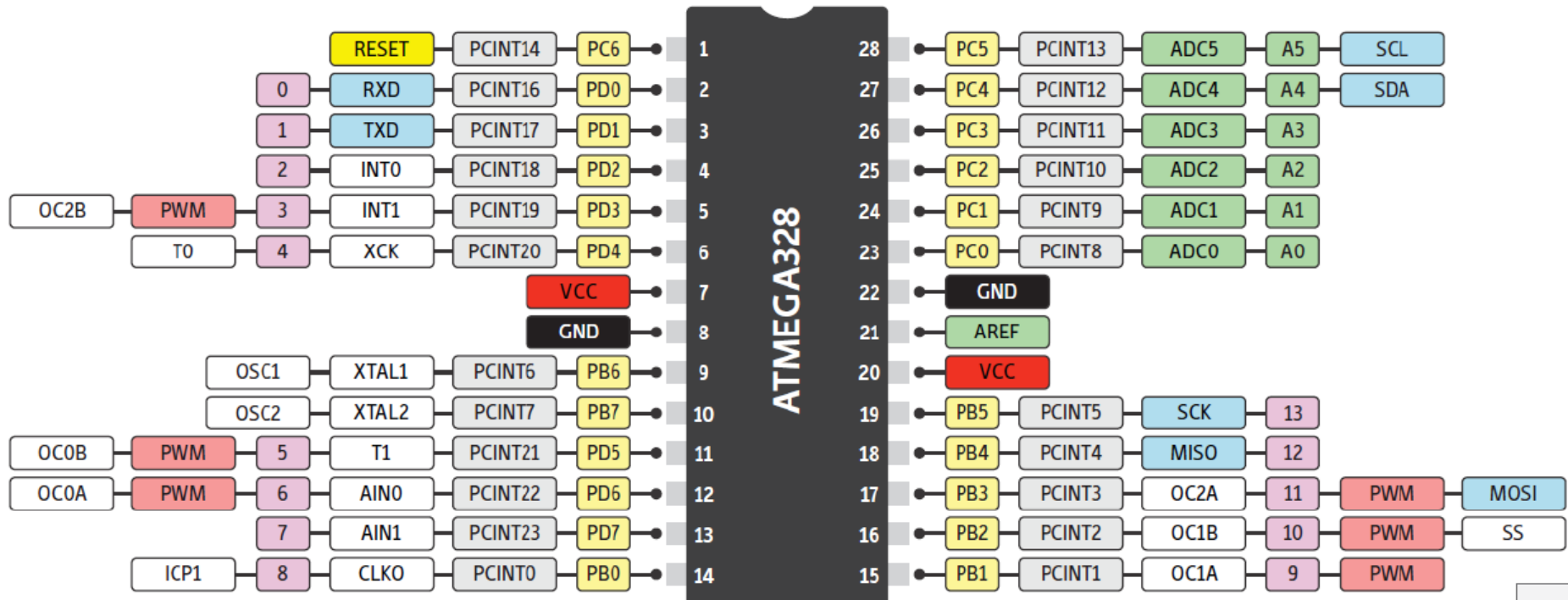


# PRIMENA MIKROKONTROLERA

## USART - Universal Synchronous Asynchronous Receiver Transceiver

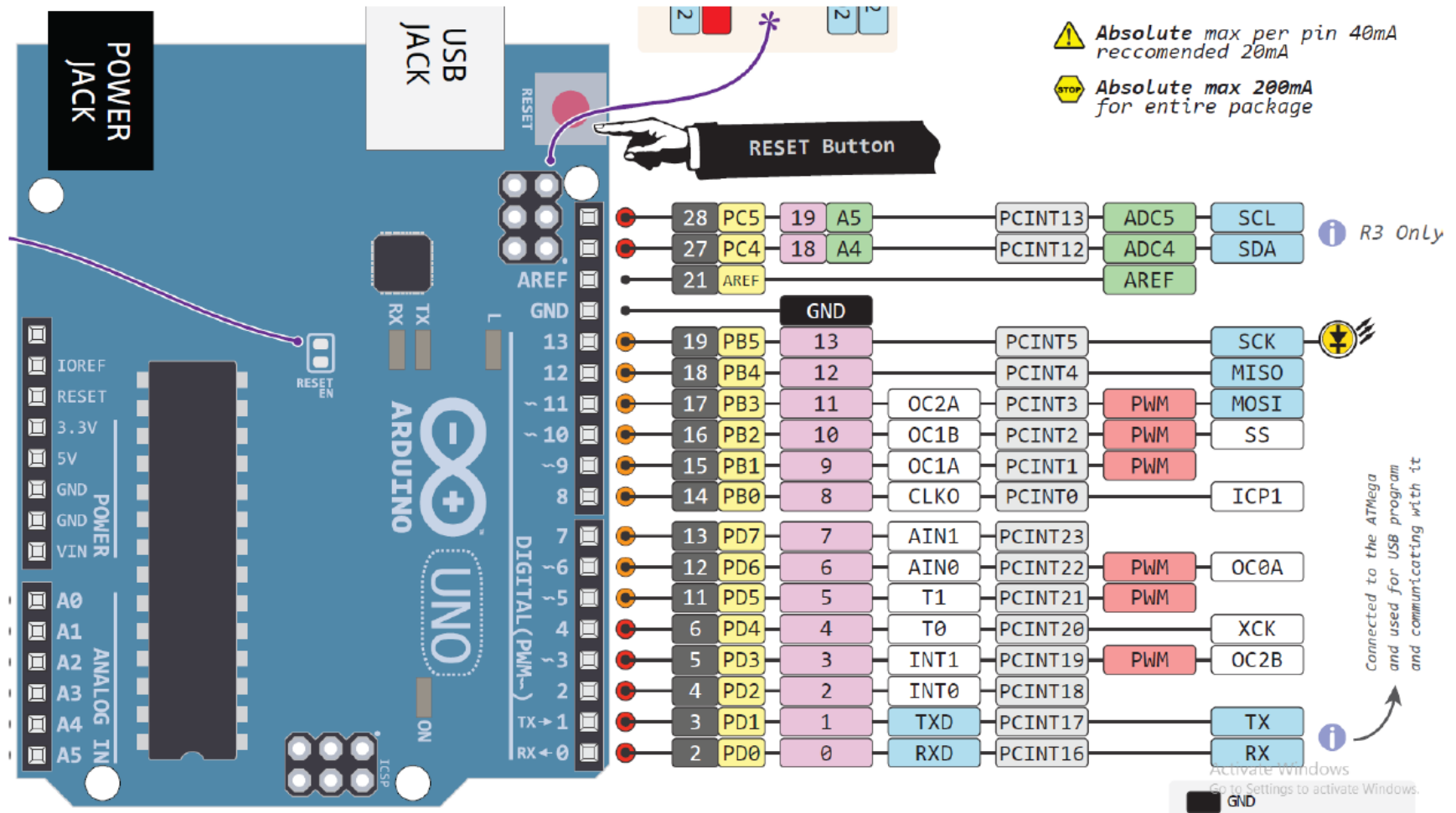
prof. dr Zoran Milivojević  
dr Nataša Nešić, viši predavač

# Mikrokontroler ATmega328P



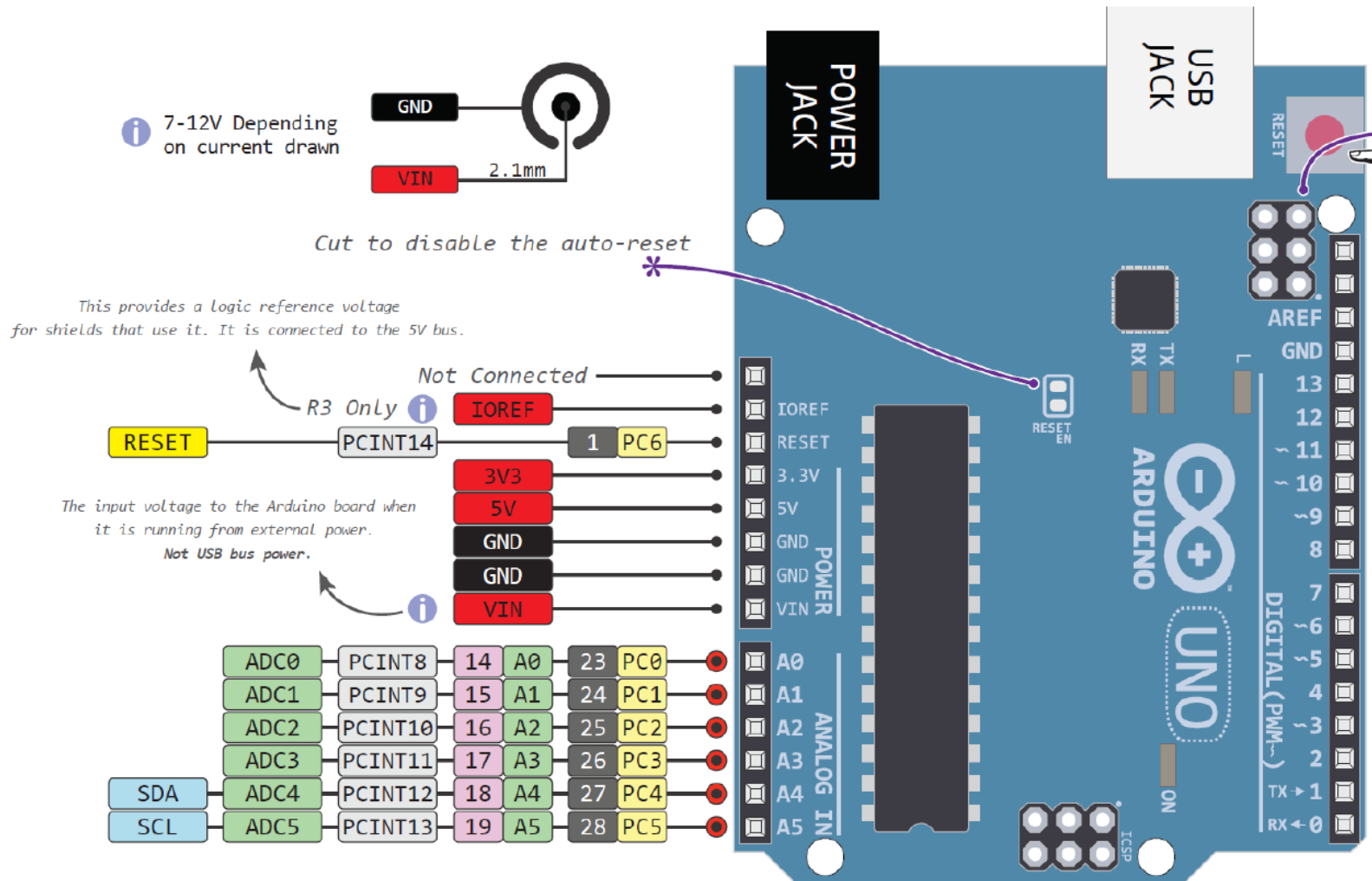
Slika 1. PINOUT dijagram mikrokontrolera ATmega328P.

# Arduino UNO

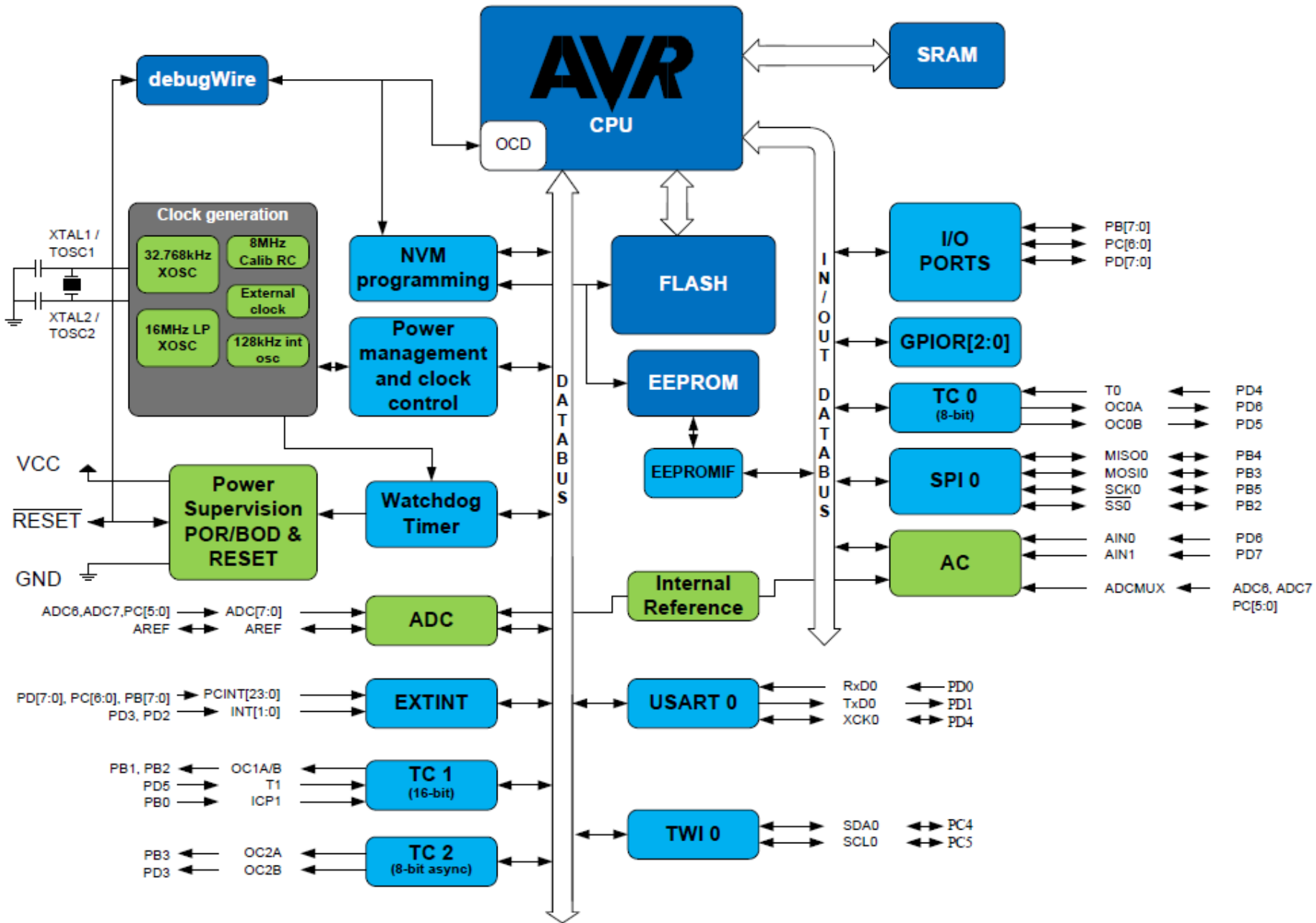


Slika 5. Deo 2 pinout dijagram Arduino UNO sistema.

# Arduino UNO



Slika 4. Deo 1 pinout dijagram Arduino UNO sistema.

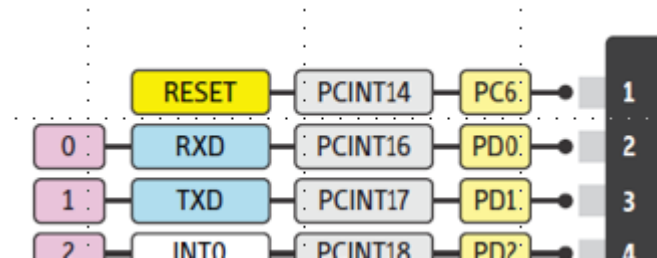
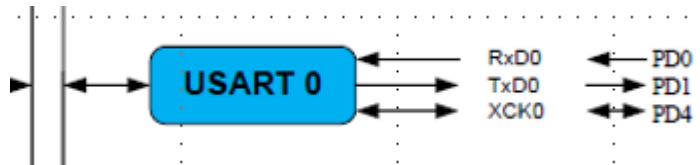


# USART - Universal Synchronous Asynchronous Receiver Transceiver

- USART stepen ATmega328 mikrokontrolera obaveđuje
  - Potpuni dupleks (nezavistan rad predajnika i prijemnika)
  - Asinhroni i sinhroni rad
  - Veliki broj brzina (Baud Rate) prenosa
  - Kontrolu parnosti
  - Tri izvora prekida

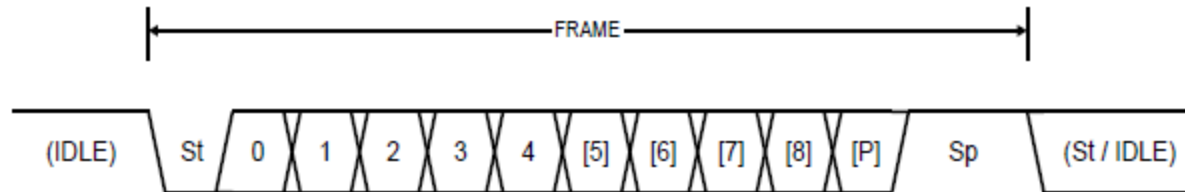
# USART

- Komunikacija sa spoljnim svetom (drugim uređajima) je prekod pinova
  - RxD0 (PD0)
  - TxD0 (PD1)



# USART – format prenosa

- 1 start bit
- 5, 6, 7, 8, or 9 data bits
- no, even or odd parity bit
- 1 or 2 stop bits



St	Start bit, always low.
(n)	Data bits (0 to 8).
P	Parity bit. Can be odd or even.
Sp	Stop bit, always high.
IDLE	No transfers on the communication line (RxDn or TxDn). An IDLE line must be high.



# USART – Brzine prenosa

- Standardne brzine prenosa (Baud Rate – bps)
  - 2400 bps
  - 4800 bps
  - 9600 bps
  - 14400 bps
  - 19200 bps
  - 28800 bps
  - 38400 bps
  - 57600 bps
  - 76000 bps
  - 115200 bps
  - 230400 bps
  - 250000 bps

# USART – kontrola rada

- Postavljanje parametara i kontrola rada USART-a ostvaruje se programskom kontrolom specijalnih registara

# USART I/O Data Register 0

**Name:** UDR0

**Offset:** 0xC6

**Reset:** 0x00

**Property:** -

Bit	7	6	5	4	3	2	1	0
	TXB / RXB[7:0]							
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

**Bits 7:0 – TXB / RXB[7:0]: USART Transmit / Receive Data Buffer**

# USART Control and Status Register 0 A

**Name:** UCSR0A

**Offset:** 0xC0

**Reset:** 0x20

**Property:** -

Bit	7	6	5	4	3	2	1	0
	RXC0	TXC0	UDRE0	FE0	DOR0	UPE0	U2X0	MPCM0
Access	R	R/W	R	R	R	R	R/W	R/W
Reset	0	0	1	0	0	0	0	0

## Bit 7 – RXC0: USART Receive Complete

This flag bit is set when there are unread data in the receive buffer and cleared when the receive buffer is empty (i.e., does not contain any unread data). If the Receiver is disabled, the receive buffer will be flushed and consequently the RXC0 bit will become zero. The RXC0 Flag can be used to generate a Receive Complete interrupt (see description of the RXCIE0 bit).

## Bit 6 – TXC0: USART Transmit Complete

This flag bit is set when the entire frame in the Transmit Shift Register has been shifted out and there are no new data currently present in the transmit buffer (UDR0). The TXC0 Flag bit is automatically cleared when a transmit complete interrupt is executed, or it can be cleared by writing a one to its bit location. The TXC0 Flag can generate a Transmit Complete interrupt (see description of the TXCIE0 bit).

#### **Bit 5 – UDRE0: USART Data Register Empty**

The UDRE0 Flag indicates if the transmit buffer (UDR0) is ready to receive new data. If UDRE0 is one, the buffer is empty, and therefore ready to be written. The UDRE0 Flag can generate a Data Register Empty interrupt (see description of the UDRIE0 bit). UDRE0 is set after a reset to indicate that the Transmitter is ready.

#### **Bit 4 – FE0: Frame Error**

This bit is set if the next character in the receive buffer had a Frame Error when received. I.e., when the first stop bit of the next character in the receive buffer is zero. This bit is valid until the receive buffer (UDR0) is read. The FEN bit is zero when the stop bit of received data is one. Always set this bit to zero when writing to UCSR0A.

This bit is reserved in Master SPI Mode (MSPIM).

#### **Bit 3 – DOR0: Data OverRun**

This bit is set if a Data OverRun condition is detected. A Data OverRun occurs when the receive buffer is full (two characters), it is a new character waiting in the Receive Shift Register, and a new start bit is detected. This bit is valid until the receive buffer (UDR0) is read. Always set this bit to zero when writing to UCSR0A.

This bit is reserved in Master SPI Mode (MSPIM).

#### **Bit 2 – UPE0: USART Parity Error**

This bit is set if the next character in the receive buffer had a Parity Error when received and the Parity Checking was enabled at that point (UPM01 = 1). This bit is valid until the receive buffer (UDR0) is read. Always set this bit to zero when writing to UCSR0A.

This bit is reserved in Master SPI Mode (MSPIM).

**Bit 1 – U2X0: Double the USART Transmission Speed**

This bit only has effect for the asynchronous operation. Write this bit to zero when using synchronous operation.

Writing this bit to one will reduce the divisor of the baud rate divider from 16 to 8 effectively doubling the transfer rate for asynchronous communication.

This bit is reserved in Master SPI Mode (MSPIM).

**Bit 0 – MPCM0: Multi-processor Communication Mode**

This bit enables the Multi-processor Communication mode. When the MPCMn bit is written to one, all the incoming frames received by the USART Receiver that do not contain address information will be ignored. The Transmitter is unaffected by the MPCM0 setting. Refer to [Multi-Processor Communication Mode](#) for details.

This bit is reserved in Master SPI Mode (MSPIM).

# USART Control and Status Register 0 B

**Name:** UCSR0B

**Offset:** 0xC1

**Reset:** 0x00

**Property:** -

Bit	7	6	5	4	3	2	1	0
	RXCIE0	TXCIE0	UDRIE0	RXEN0	TXEN0	UCSZ02	RXB80	TXB80
Access	R/W	R/W	R/W	R/W	R/W	R/W	R	R/W
Reset	0	0	0	0	0	0	0	0

## **Bit 7 – RXCIE0: RX Complete Interrupt Enable 0**

Writing this bit to one enables interrupt on the RXC0 Flag. A USART Receive Complete interrupt will be generated only if the RXCIE0 bit is written to one, the Global Interrupt Flag in SREG is written to one and the RXC0 bit in UCSR0A is set.

## **Bit 6 – TXCIE0: TX Complete Interrupt Enable 0**

Writing this bit to one enables interrupt on the TXC0 Flag. A USART Transmit Complete interrupt will be generated only if the TXCIE0 bit is written to one, the Global Interrupt Flag in SREG is written to one and the TXC0 bit in UCSR0A is set.

## **Bit 5 – UDRIE0: USART Data Register Empty Interrupt Enable 0**

Writing this bit to one enables interrupt on the UDRE0 Flag. A Data Register Empty interrupt will be generated only if the UDRIE0 bit is written to one, the Global Interrupt Flag in SREG is written to one and the UDRE0 bit in UCSR0A is set.

#### **Bit 4 – RXEN0: Receiver Enable 0**

Writing this bit to one enables the USART Receiver. The Receiver will override normal port operation for the RxDn pin when enabled. Disabling the Receiver will flush the receive buffer invalidating the FE0, DOR0, and UPE0 Flags.

#### **Bit 3 – TXEN0: Transmitter Enable 0**

Writing this bit to one enables the USART Transmitter. The Transmitter will override normal port operation for the TxD0 pin when enabled. The disabling of the Transmitter (writing TXEN0 to zero) will not become effective until ongoing and pending transmissions are completed, i.e., when the Transmit Shift Register and Transmit Buffer Register do not contain data to be transmitted. When disabled, the Transmitter will no longer override the TxD0 port.

#### **Bit 2 – UCSZ02: Character Size 0**

The UCSZ02 bits combined with the UCSZ0[1:0] bit in UCSR0C sets the number of data bits (Character Size) in a frame the Receiver and Transmitter use.

This bit is reserved in Master SPI Mode (MSPIM).

#### **Bit 1 – RXB80: Receive Data Bit 8 0**

RXB80 is the ninth data bit of the received character when operating with serial frames with nine data bits. Must be read before reading the low bits from UDR0.

This bit is reserved in Master SPI Mode (MSPIM).

#### **Bit 0 – TXB80: Transmit Data Bit 8 0**

TXB80 is the ninth data bit in the character to be transmitted when operating with serial frames with nine data bits. Must be written before writing the low bits to UDR0.

This bit is reserved in Master SPI Mode (MSPIM).



# USART Control and Status Register 0 C

**Name:** UCSR0C

**Offset:** 0xC2

**Reset:** 0x06

**Property:** -

Bit	7	6	5	4	3	2	1	0
	UMSEL01	UMSEL00	UPM01	UPM00	USBS0	UCSZ01 / UDORD0	UCSZ00 / UCPHA0	UCPOL0
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	1	1	0

## Bits 7:6 – UMSEL0n: USART Mode Select 0 n [n = 1:0]

These bits select the mode of operation of the USART0

Table 24-8. USART Mode Selection

UMSEL0[1:0]	Mode
00	Asynchronous USART
01	Synchronous USART
10	Reserved
11	Master SPI (MSPIM) <sup>(1)</sup>

**Bits 5:4 – UPM0n: USART Parity Mode 0 n [n = 1:0]**

These bits enable and set type of parity generation and check. If enabled, the Transmitter will automatically generate and send the parity of the transmitted data bits within each frame. The Receiver will generate a parity value for the incoming data and compare it to the UPM0 setting. If a mismatch is detected, the UPE0 Flag in UCSR0A will be set.

**Table 24-9. USART Mode Selection**

UPM0[1:0]	ParityMode
00	Disabled
01	Reserved
10	Enabled, Even Parity
11	Enabled, Odd Parity

These bits are reserved in Master SPI Mode (MSPIM).

**Bit 3 – USBS0: USART Stop Bit Select 0**

This bit selects the number of stop bits to be inserted by the Transmitter. The Receiver ignores this setting.

**Table 24-10. Stop Bit Settings**

<b>USBS0</b>	<b>Stop Bit(s)</b>
0	1-bit
1	2-bit

This bit is reserved in Master SPI Mode (MSPIM).

**Bit 2 – UCSZ01 / UDORD0: USART Character Size / Data Order**

**UCSZ0[1:0]: USART Modes:** The UCSZ0[1:0] bits combined with the UCSZ02 bit in UCSR0B sets the number of data bits (Character Size) in a frame the Receiver and Transmitter use.

**Table 24-11. Character Size Settings**

<b>UCSZ0[2:0]</b>	<b>Character Size</b>
000	5-bit
001	6-bit
010	7-bit
011	8-bit
100	Reserved
101	Reserved
110	Reserved
111	9-bit

**UDPRD0: Master SPI Mode:** When set to one the LSB of the data word is transmitted first. When set to zero the MSB of the data word is transmitted first. Refer to the *USART in SPI Mode - Frame Formats* for details.

**Bit 1 – UCSZ00 / UCPHA0: USART Character Size / Clock Phase**

**UCSZ00: USART Modes:** Refer to UCSZ01.

**UCPHA0: Master SPI Mode:** The UCPHA0 bit setting determine if data is sampled on the leading edge (first) or trailing (last) edge of XCK0. Refer to the *SPI Data Modes and Timing* for details.

**Bit 0 – UCPOL0: Clock Polarity 0**

**USART0 Modes:** This bit is used for synchronous mode only. Write this bit to zero when asynchronous mode is used. The UCPOL0 bit sets the relationship between data output change and data input sample, and the synchronous clock (XCK0).

**Table 24-12. USART Clock Polarity Settings**

UCPOL0	Transmitted Data Changed (Output of TxD0 Pin)	Received Data Sampled (Input on RxD0 Pin)
0	Rising XCK0 Edge	Falling XCK0 Edge
1	Falling XCK0 Edge	Rising XCK0 Edge

# USART Baud Rate 0 Register

Bit	7	6	5	4	3	2	1	0
	UBRR0[7:0]							
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

## Bits 7:0 – UBRR0[7:0]: USART Baud Rate 0

This is a 12-bit register which contains the USART baud rate. The UBRR0H contains the four most significant bits and the UBRR0L contains the eight least significant bits of the USART baud rate. Ongoing transmissions by the Transmitter and Receiver will be corrupted if the baud rate is changed. Writing UBRR0L will trigger an immediate update of the baud rate prescaler.

**Name:** UBRR0H  
**Offset:** 0xC5  
**Reset:** 0x00  
**Property:** -

Bit	7	6	5	4	3	2	1	0
					UBRR0[3:0]			
Access					R/W	R/W	R/W	R/W
Reset					0	0	0	0

## Bits 3:0 – UBRR0[3:0]: USART Baud Rate 0 n [n = 11:8]

• **HVALA NA PAŽNJI**